

EMU PRO 8 Pinout v1.0

Connector symbols:



Connector part numbers:

Connector series		AMP SUPERSEAL 1.	0
Connector A	4-1437290-1	34 Positions	Keys: 2 top, 2 bottom
Connector B	1473416-1	26 Positions	Keys: 3 top, 2 bottom
Connector C 4-1437290-0 34 Positions Keys: 2 f		Keys: 2 top, 1 bottom	
Terminal	1-1437284-0	14	-16 AWG
Terminal	3-1447221-3	16-18 AWG	
Terminal	3-1447221-4	20 AWG	
Terminal	3-1447221-5	22 AWG	

Power pins		
Name	Count	Description
+12V supply	2	Power supply for the ECU and H-bridges.
		Can be connected as constant or switched battery voltage.
		Delayed turn off will only function with constant supply.
+12V switched	1	+12V input to switch the ECU on or off.
		Should be connected to +12V after the ignition switch.
Power GND	5	Power ground.
		All power ground pins must be connected to the main ground point (chassis, engine, battery). ECU supply and current from every output switched to ground flows through those pins.
+5V source A/B	4	+5V sensor supply.
		There are two separate sources, A & B. Each source can provide up to 2 A of current.
Digital GND	2	Digital ground.
		Digital signals (frequency, duty cycle, switches) must be connected between digital input and digital ground. Do not connect those pins to the external ground point or other ground pins.
Analog GND	1	Analog ground.
		Analog signals (voltage) must be connected between the analog input and analog ground. Do not connect those pins to the external ground point or other ground pins.



Communication pins		
Name	Count	Description
CAN 1 high/low	2	CAN bus, fixed 1 Mbps, used for communication with PC and peripheral devices.
		Communication with PC software can only be done through this CAN bus.
		No internal termination resistor. External termination is required.
		Fully configurable communication.
CAN 2 high/low	2	CAN bus, configurable speed, used for communication with peripheral devices.
		Configurable speed: 125, 250, 500, and 1000 kbps.
		Software controlled termination resistor.
		Fully configurable communication.
LIN	1	LIN network.
		Communication with peripheral LIN devices.
USB D-, D+	2	USB data pins.
		Pins used to connect a flash drive for data logging. A group of pins from B9 to B12 should be used when connecting a USB socket.

nput pins		
Name	Count	Description
Digital	8	Digital signal input. Input for digital signals (frequency, duty cycle, switches). Digital signals must be connected between these inputs and digital ground. Inductive (VR), HALL, or magnetoresistive (MR) sensors can be used. Digital 1 is dedicated to the crankshaft position sensor. Turboshaft speed sensors can only be connected to Digital 5 & 6. Configurable voltage threshold: 0-5 V. Configurable pull resistor: disabled, 1 k Ω pull up, or 1 k Ω pull down. Configurable input filter strength: disabled, low, medium, or high. Maximum voltage for Digital 1: 120 V. Maximum voltage for other inputs: 50 V.
Analog	16	Analog signal input. Input for analog signals (voltage). Analog signals must be connected between these inputs and analog ground. Analog 1 is dedicated to the manifold pressure sensor. Configurable pull resistor: disabled, pull up, or pull down. Analogs 1-8 have a 10 k Ω pull resistor. Analogs 9-12 have a 2.2 k Ω pull resistor. Recommended for thermistors. Analogs 13-14 have a 1 k Ω pull resistor. Recommended for thermistors. Analogs 15-16 don't have pull down option. Only disabled or pull up. Analog 15 has a 330 Ω pull resistor. Recommended for low resistance thermistors. Analog 16 has a 100 Ω pull resistor. Recommended for fuel level sensors. Measurement frequency: 500 Hz. Measurement resolution: 12 bit. Measurement voltage range: 0-5 V. Maximum input voltage: 20 V.
Knock sensor	2	Knock sensor input. Input for knock sensor signals (voltage). Knock sensor signals must be connected between these inputs and analog ground. Configurable gain. Configurable frequency of the input filter. Maximum input voltage: 14 V.



Input pins		
Name	Count	Description
Precision analog	4	High precision analog input.
		Input for analog signals (voltage) that require higher resolution. Possibility to directly connect type K thermocouples. Analog signals must be connected between these inputs and analog ground or between 2 adjacent inputs. Recommended for EGT sensors (exhaust gas temperature). Differential measurement is done between two adjacent inputs (1+2, 3+4). Configurable pull resistor: disabled, 10 k Ω pull up, or 10 k Ω pull down. Configurable measurement range: 0-512 mV or 0-5 V. Cold junction compensation for type K thermocouples. Measurement frequency: 40 Hz. Measurement resolution: 16 bit. Maximum input voltage: 5 V.
WBO	8	Wideband oxygen sensor inputs. Inputs for the wideband oxygen sensor LSU 4.9. There are two separate oxygen sensor controllers. Sensor heaters can be connected to auxiliary outputs 1-4.

Output pins

Name	Count	Description
Injector	8	Output for high or low impedance injectors.
		Low side output for injectors as well as auxiliary devices. Can control low impedance injectors directly with peak & hold strategy. Can be used as an auxiliary output with on/off, PWM, or current control mode. The load can be disconnected (Hi-Z) or connected to the ground (GND). Short circuit/overcurrent protection. Open load detection. Current measurement. Integrated flyback diode. Turn off voltage clamp: 36 V. Maximum PWM frequency: 2000 Hz. Maximum peak current: 8 A. Maximum constant current: 5 A.
Ignition	8	Output for active or passive ignition coils.
		Output for controlling active or passive ignition coils. Coil type configurable in software. Active coil high voltage level: 8 V. Maximum current for active coils: 80 mA. Maximum peak current: 15 A.
Auxiliary	12	Output for auxiliary devices.
		Low side output for auxiliary devices with on/off, PWM, or current control mode. The load can be disconnected (Hi-Z) or connected to the ground (GND). Short circuit/overcurrent protection. Open load detection. Current measurement. Integrated flyback diode. Integrated 10kΩ pull up resistor to +12V. Maximum PWM frequency: 2000 Hz. Maximum constant current: 5 A.
H-bridge	6	H-bridge output.
		Push-pull output from the h-bridge driver. Can be used as a single output or a full h-bridge with two outputs. In single output mode, only outputs 1B, 2B, 3B, and 4B can be used with PWM. The load can be connected to supply (+12 V) or connected to the ground (GND). Short circuit, overcurrent, and overtemperature protection. Configurable current limit. Maximum PWM frequency: 8000 Hz. Maximum constant current: 7 A.



Connector A:



Pin	Name	Description
A1	Ignition 8	Output for active or passive ignition coils.
A2	Injector 1	Output for high or low impedance injectors.
A3	Injector 2	Output for high or low impedance injectors.
A4	Injector 3	Output for high or low impedance injectors.
A5	Injector 4	Output for high or low impedance injectors.
A6	Injector 5	Output for high or low impedance injectors.
A7	Injector 6	Output for high or low impedance injectors.
A8	Injector 7	Output for high or low impedance injectors.
A9	Injector 8	Output for high or low impedance injectors.
A10	Ignition 7	Output for active or passive ignition coils.
A11	Power GND	Power ground.
A12	+5V source A	+5V sensor supply, source A.
A13	Digital 2	Digital signal input.
A14	Digital 4	Digital signal input.
A15	Digital 8	Digital signal input.
A16	Digital 6 (turbo)	Digital signal input, can be used for turboshaft speed sensor.
A17	Power GND	Power ground.
A18	Ignition 6	Output for active or passive ignition coils.
A19	Power GND	Power ground.
A20	Digital GND	Digital ground.
A21	Digital 1 (crank)	Digital signal input, dedicated crankshaft sensor input.
A22	Digital 3	Digital signal input.
A23	Digital 7	Digital signal input.
A24	Digital 5 (turbo)	Digital signal input, can be used for turboshaft speed sensor.
A25	Auxiliary 9	Output for auxiliary devices.
A26	Ignition 5	Output for active or passive ignition coils.
A27	Ignition 4	Output for active or passive ignition coils.
A28	Ignition 3	Output for active or passive ignition coils.
A29	Ignition 2	Output for active or passive ignition coils.
A30	Ignition 1	Output for active or passive ignition coils.
A31	CAN 1 high (PC comm)	CAN bus, fixed 1Mbps, used for communication with PC and peripheral devices.
A32	CAN 1 low (PC comm)	CAN bus, fixed 1Mbps, used for communication with PC and peripheral devices.
A33	CAN 2 high	CAN bus, configurable speed, used for communication with peripheral devices.
A34	CAN 2 low	CAN bus, configurable speed, used for communication with peripheral devices.





Pin	Name	Description
B1	Auxiliary 1 (WBO heater)	Output for auxiliary devices, can be used as a WBO heater.
B2	Auxiliary 2 (WBO heater)	Output for auxiliary devices, can be used as a WBO heater.
B3	Auxiliary 3 (WBO heater)	Output for auxiliary devices, can be used as a WBO heater.
B4	Auxiliary 4 (WBO heater)	Output for auxiliary devices, can be used as a WBO heater.
B5	Auxiliary 5	Output for auxiliary devices.
B6	Auxiliary 6	Output for auxiliary devices.
B7	Auxiliary 7	Output for auxiliary devices.
B8	+12V supply	Power supply for the ECU and H-bridges.
B9	Digital GND (flash drive)	Digital ground, recommended for flash drive connection.
B10	USB D- (flash drive)	USB data pin for a flash drive, data logging.
B11	USB D+ (flash drive)	USB data pin for a flash drive, data logging.
B12	+5V source A (flash drive)	+5V sensor supply, source A, recommended for flash drive connection.
B13	Auxiliary 8	Output for auxiliary devices.
B14	+12V supply	Power supply for the ECU and H-bridges.
B15	+12V switched	+12V input to switch the ECU on or off.
B16	Knock sensor 1	Knock sensor input.
B17	Knock sensor 2	Knock sensor input.
B18	WBO 2 VGND (LSU 4.9)	Wideband oxygen sensor input, LSU 4.9 Pin 2 (IPN / VM).
B19	Power GND	Power ground.
B20	WBO 1 IP (LSU 4.9)	Wideband oxygen sensor input, LSU 4.9 Pin 1 (APE / IP).
B21	WBO 1 VS (LSU 4.9)	Wideband oxygen sensor input, LSU 4.9 Pin 6 (UN / RE).
B22	WBO 1 RCAL (LSU 4.9)	Wideband oxygen sensor input, LSU 4.9 Pin 5 (RT / IA).
B23	WBO 1 VGND (LSU 4.9)	Wideband oxygen sensor input, LSU 4.9 Pin 2 (IPN / VM).
B24	WBO 2 IP (LSU 4.9)	Wideband oxygen sensor input, LSU 4.9 Pin 1 (APE / IP).
B25	WBO 2 VS (LSU 4.9)	Wideband oxygen sensor input, LSU 4.9 Pin 6 (UN / RE).
B26	WBO 2 RCAL (LSU 4.9)	Wideband oxygen sensor input, LSU 4.9 Pin 5 (RT / IA).



Connector C:



Pin	Name	Description
C1	Auxiliary 10	Output for auxiliary devices.
C2	Auxiliary 11	Output for auxiliary devices.
C3	Auxiliary 12	Output for auxiliary devices.
C4	Analog 7	Analog signal input.
C5	Analog 10 (2k2 pull)	Analog signal input.
C6	H-bridge 1A	H-bridge output.
C7	H-bridge 2B	H-bridge output.
C8	H-bridge 3A	H-bridge output.
C9	H-bridge 2A	H-bridge output.
C10	Analog 1 (MAP)	Analog signal input, dedicated MAP sensor input.
C11	Analog 3	Analog signal input.
C12	Analog 5	Analog signal input.
C13	Analog 8	Analog signal input.
C14	Analog 11 (2k2 pull)	Analog signal input.
C15	Analog 13 (1k pull)	Analog signal input.
C16	Analog 15 (330R pull)	Analog signal input.
C17	H-bridge 3B	H-bridge output.
C18	Analog 2	Analog signal input.
C19	Analog 4	Analog signal input.
C20	Analog 6	Analog signal input.
C21	Analog 9 (2k2 pull)	Analog signal input.
C22	Analog 12 (2k2 pull)	Analog signal input.
C23	Analog 14 (1k pull)	Analog signal input.
C24	Analog 16 (100R pull)	Analog signal input.
C25	H-bridge 1B	H-bridge output.
C26	LIN	LIN network.
C27	+5V source B	+5V sensor supply, source B.
C28	+5V source B	+5V sensor supply, source B.
C29	Analog GND	Analog ground.
C30	Power GND	Power ground.
C31	Precision analog 1	High precision analog input.
C32	Precision analog 2	High precision analog input.
C33	Precision analog 3	High precision analog input.
C34	Precision analog 4	High precision analog input.



Document revision history:

Revision	Date	Changes
1.0	2023-02-24	- first public version